DYNAMIC OBSTACLE TRACKING

Avoid collisions and employ safer passage in the warehouse

Allows for smoother motion around pedestrian traffic, forklifts, or any other moving vehicles. The tracking algorithm projects the path of moving objects in the same space as the robot to avoid collisions and traffic jams. If a person is walking in the path perpendicular to the robot, rather than trying to cross in front of the person's path, a robot with Dynamic Obstacle Tracking will slow down and move behind the person.

FLEET OPERATIONS WORKSPACE CORE